

Final - Computer Science 2 (2020-21)

Time: 3 hours.

Attempt all questions, giving proper explanations.

You may quote any result proved in class without proof.

1. How is the number 22.5 stored as a floating point number in the computer ? Give the sign, mantissa and exponent. [4 marks]
2. (a) How many floating point numbers are there in $[0, 1]$? [2 marks]
(b) How many floating point numbers are there in $[1, \text{Machine\$double.xmax}]$? [2 marks]
(c) Are the number of floating point numbers in $[0, 1]$ equal to the number of floating point numbers in $2 + [0, 1] = [2, 3]$? Explain. [2 marks]
3. Consider the solution to $x = g(x)$ in $[0, 1]$ where $g(x) = \frac{1}{4}(1 - x)^4$. Consider the iterations $x_{k+1} = g(x_k)$. Starting from $x_0 = \frac{1}{2}$ roughly how many iterations are necessary before we are within 10^{-6} of the solution? [4 marks]
4. Consider the equation $x^2 - 3 = 0$.
(a) Show, starting from $x_0 = 1$, that Newton's method converges to $\sqrt{3}$. [4 marks]
(b) For what values of x_0 does Newton's method converge to $\sqrt{3}$? It is enough to give a non-rigorous explanation. [2 marks]
5. Consider the matrix \mathbf{A} and the vector \mathbf{b} given below.

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 2 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{bmatrix}, \quad \mathbf{b} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 3 \end{pmatrix}$$

- (a) Find the QR decomposition of \mathbf{A} . [4 marks]
(b) Find the least squares solution of the system $\mathbf{Ax} = \mathbf{b}$. [2 marks]
6. Consider an infinitely differentiable function $f : [0, 1] \rightarrow \mathbf{R}$.
(a) Write down the Newton-Cotes formula for $\int_0^1 f(x)dx$ with 4 equally spaced points $0 = x_0 < x_1 < x_2 < x_3 = 1$. [4 marks]
(b) What is the error in approximating the integral by the approximation? [2 marks]
7. For this problem you may use \mathbf{R} for some of the computations.
(a) Find a set of points $x_0, x_1, x_2 \in [0, 1]$ such that for any $f \in \mathcal{P}_5$, the set of polynomials of degree at most 5, we have

$$\int_0^1 f(x)dx = \int_0^1 p_2(x)dx$$

where $p_2(x)$ is the Lagrange polynomial passing through the points $(x_i, f(x_i))$, $i = 0, 1, 2$. [5 marks]

Note: If you require to find the roots of a polynomial $a_0 + a_1x + a_2x^2 + \dots + a_nx^n$, type `polyroot(z=c(a_0, a_1, a_2, ..., a_n))` in \mathbf{R} .

- (b) For any $f \in \mathcal{P}_5$ write down $\int_0^1 f(x)dx$ as a linear combination of $f(x_i)$, $i = 0, 1, 2$, where x_i are computed above. [3 marks]
- (c) Explain why this quadrature rule is better than the Simpson quadrature rule. [1 mark]

8. Consider the solution $(x(t), y(t))$, $0 \leq t \leq \frac{3}{4}$, to the *system* of differential equations:

$$\begin{aligned}\frac{dx}{dt} &= (x+2)^2, & x(0) &= -1, \\ \frac{dy}{dt} &= x, & y(0) &= 0.\end{aligned}$$

For $h > 0$, we use the Euler approximation :

$$\begin{aligned}x_{i+1} &= x_i + h(x_i + 2)^2, \\ y_{i+1} &= y_i + hx_i.\end{aligned}$$

with $x_0 = -1$, $y_0 = 0$ and (x_i, y_i) the approximation at the point $t_i = ih$. Show that

$$y_{[\frac{1}{2h}] + 1} - y_{[\frac{1}{2h}]} = O(h^2).$$

(Above $[a]$ denotes the integer part of a .) [4 marks]